

# Using Raspberry Pi & Node-Red to Open/Close a Garage Door

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# Raspberry Pi

- Single Board Computer
  - Credit card size or smaller
  - Developed in UK mainly for educational purposes
  - First model released in Feb 2012, lately updates released on Pi Day (3.14)
  - Generally run Linux operating system – Raspbian
  - Current models:
    - Raspberry Pi 3+ B – \$35 for 4 core 1.4Ghz, 1 GB mem, 4x USB, connections for Ethernet, WiFi, BLE, camera, audio/video, HDMI
    - Raspberry Pi Zero W - \$10 for 1 Ghz, 1GB mem, connections for WiFi, BLE, 1 micro USB, mini HDMI

# Node-Red

- Web browser-based flow editor
- Developed by IBM, became open-source in 2016
- Internally written in JavaScript (runs under Google's JavaScript engine used in browsers) programs with JSON data files
- A Message (MSG) object passes from one node to another ("readable" JSON object). MSG fields:
  - Payload [this is generally the field that is important]
  - Topic [usually used for MQTT topics]
  - {user can add other fields as desired}
- Flows or part flow are Exported or Imported as text file
  - Makes for very easy code sharing
- Add-on nodes or pallets also distributed as readable JavaScript code

# Setup/Update Node-Red on Pi

- See [Node-Red on Raspberry Pi](#) and run  
`bash <(curl -sL https://raw.githubusercontent.com/node-red/raspbian-deb-package/master/resources/update-nodejs-and-nodered)`
- Above will update to latest version plus add Pi specific nodes (being used today)
- Above web page also shows how to setup node-red to start automatically at system start
- Manually start in cmd window “node-red-start”
- Access via web at:
  - Design window: <http://{ip address of Pi}:1880>
  - Dashboard: <http://{ip address of Pi}:1880/ui>

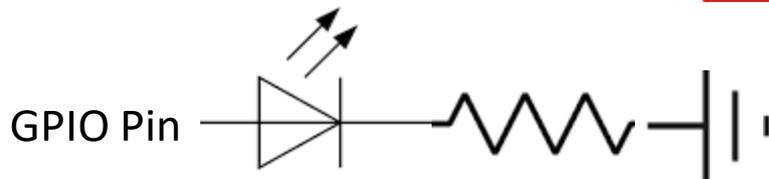
# First steps

- On test Pi I already added *node-red-dashboard* & *node-red-node-pisrf* pallets
- Review pallets nodes
- Flow
  - A way to separate “code”
  - can use links between flows to send/receive messages
- First flow: Inject + Debug
- Export, Delete All, Import
- Dashboard
  - Tabs, Groups, Order
  - Switch + Debug
  - Red, Green, Blue lights
  - All Off button

# Connecting Raspberry Pi to Outside World - pin # vs GPIO

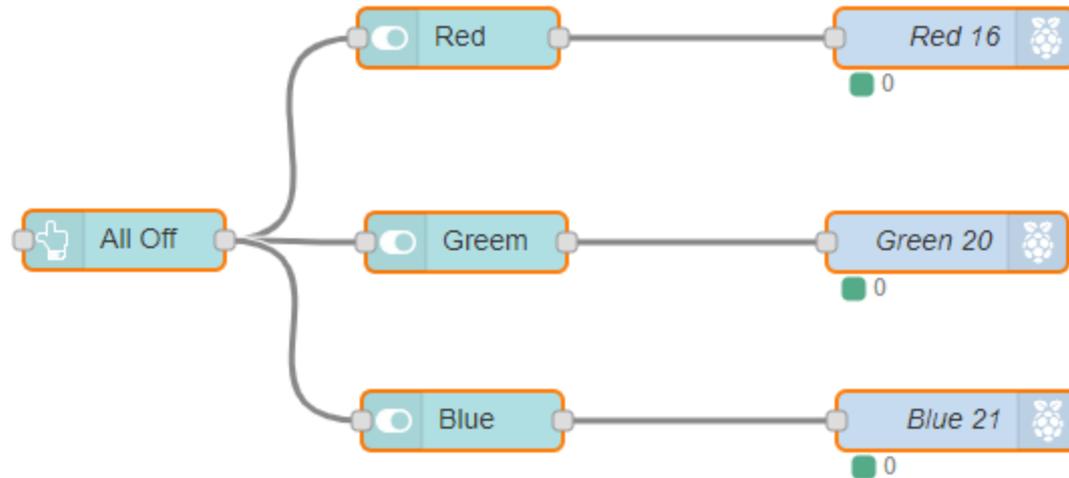


Alternate Function	Pin #	Pin #	Alternate Function
	3.3V PWR	1	2 5V PWR
I2C1 SDA	GPIO 2	3	4 5V PWR
I2C1 SCL	GPIO 3	5	6 GND
	GPIO 4	7	8 UART0 TX
	GND	9	10 UART0 RX
	GPIO 17	11	12 GPIO 18
	GPIO 27	13	14 GND
	GPIO 22	15	16 GPIO 23
	3.3V PWR	17	18 GPIO 24
SPI0 MOSI	GPIO 10	19	20 GND
SPI0 MISO	GPIO 9	21	22 GPIO 25
SPI0 SCLK	GPIO 11	23	24 GPIO 8
	GND	25	26 GPIO 7
	Reserved	27	28 Reserved
	GPIO 5	29	30 GND
	GPIO 6	31	32 GPIO 12
	GPIO 13	33	34 GND
SPI1 MISO	GPIO 19	35	36 GPIO 16
	GPIO 26	37	38 GPIO 20
	GND	39	40 GPIO 21

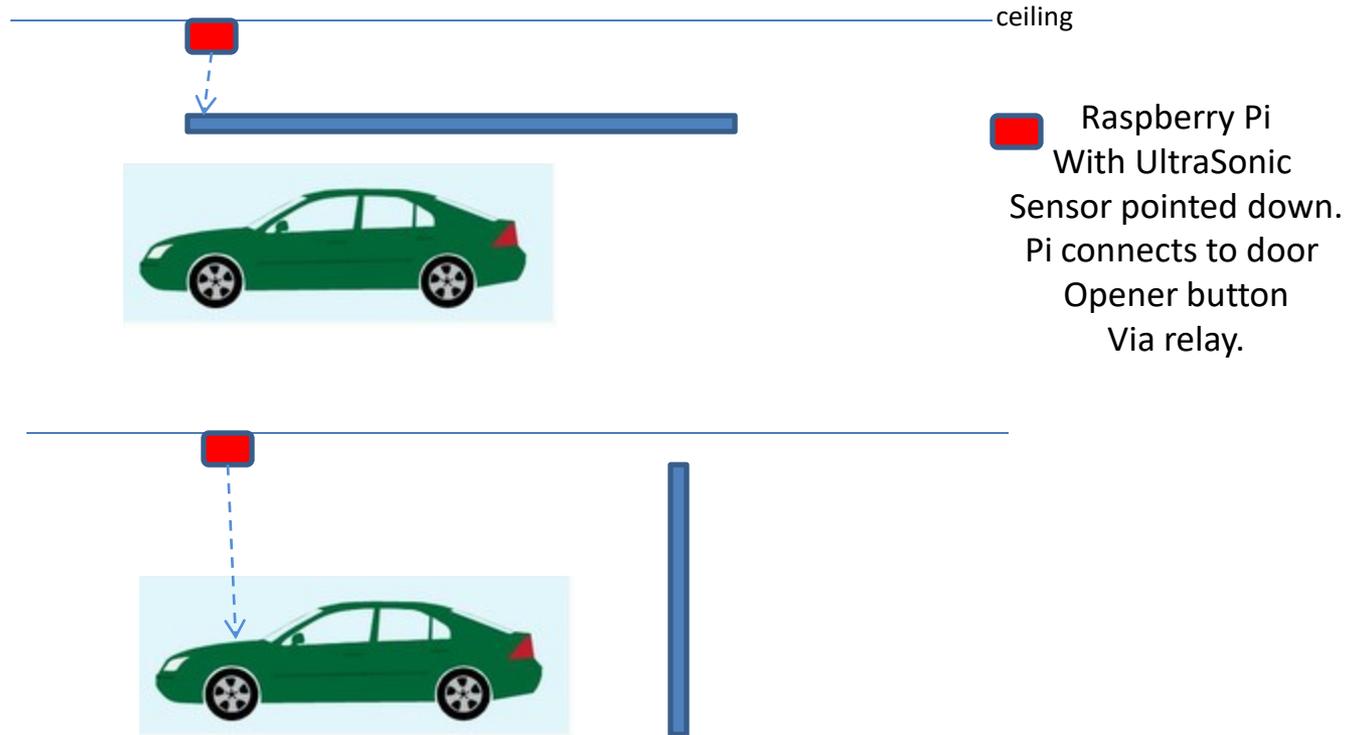


Red = 16, Green = 20, Blue = 21, Ground = 6

# Demo Flow



# Garage Door



UltraSonic sensor gives distance to object, car present and door down, door up.

# UltraSonic

- Pallet: node-red-node-pisrf
  - Requires two GPIO pin numbers, the trigger pin and the echo pin
  - Measures in centimeters (limit 5 meters)
  - Produces one measure every 0.5s (by default) - but only if the distance is different from the previous reading.

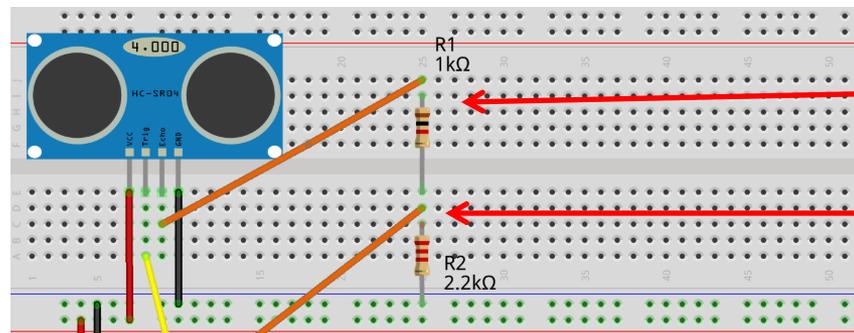


## HC-SR04 Specifications

- Working Voltage: DC 5V
- Working Current: 15mA
- Working Frequency: 40Hz
- Max Range: 4m
- Min Range: 2cm
- Measuring Angle: 15 degree
- Trigger Input Signal: 10 $\mu$ S TTL pulse
- Echo Output Signal Input TTL lever signal and the range in proportion
- Dimension 45 \* 20 \* 15mm

# Protect Your Raspberry Pi

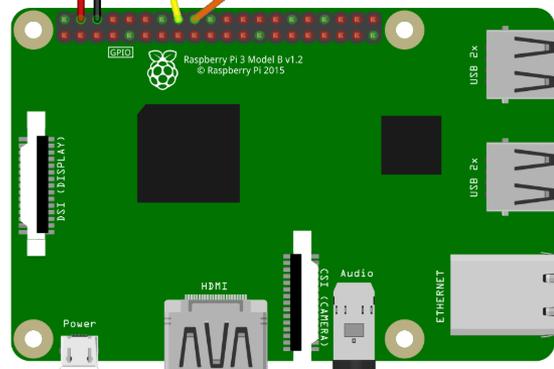
- HC-SR04 requires 5v for power (newer version can use 3.3v) but 5v is too much for Raspberry Pi (can burn out port / computer). Use voltage divider to reduce signal line.



5v

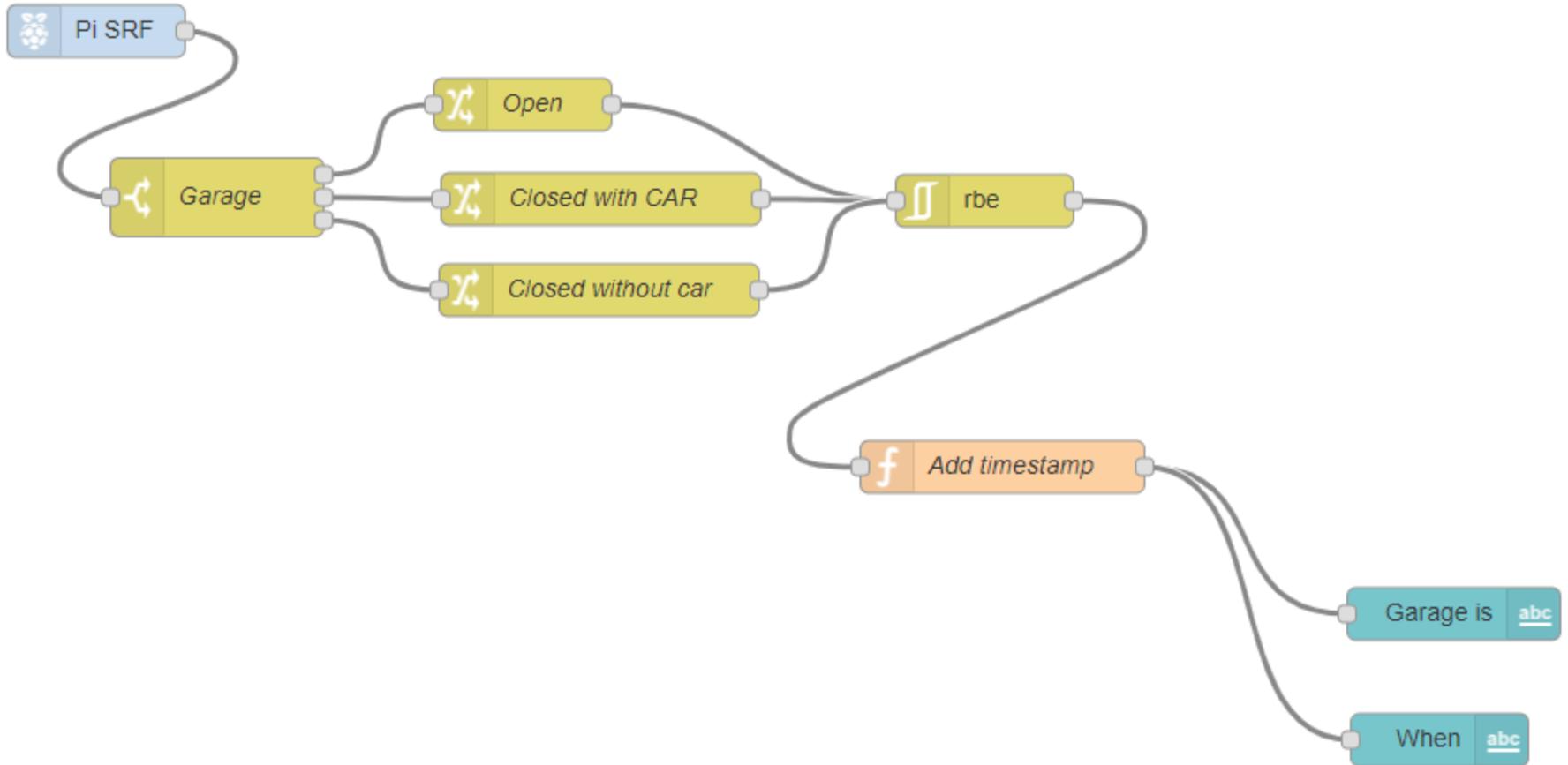
$$3.3v = \frac{5v * 2.2K}{1K+2.2K}$$

Echo Output  
Signal to Pi



Trig <-> GPIO 23  
Echo <-> GPIO 24  
Vcc == 5v

# Demo Flow



Thanks to work done by John Scott!

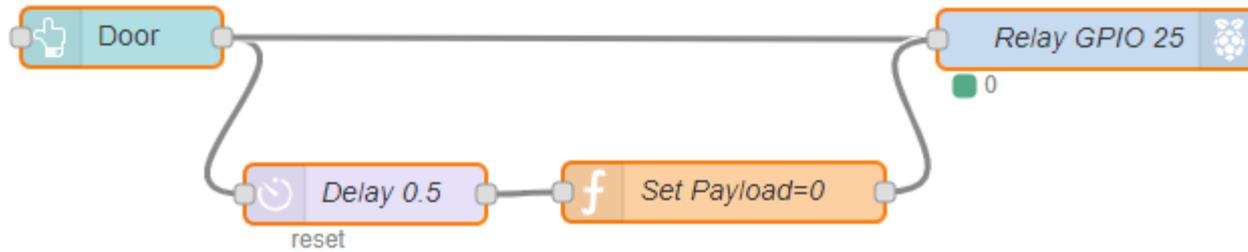
# Relay to Activate Door Opener

- Use relay to isolate Pi from Opener
- Connect Normally Open connections in parallel with the current opener button
- Connect signal pin to spare gpio – send a 1 to “push button”, wait 0.5 seconds and revert to 0 (don’t want to hold down button too long)



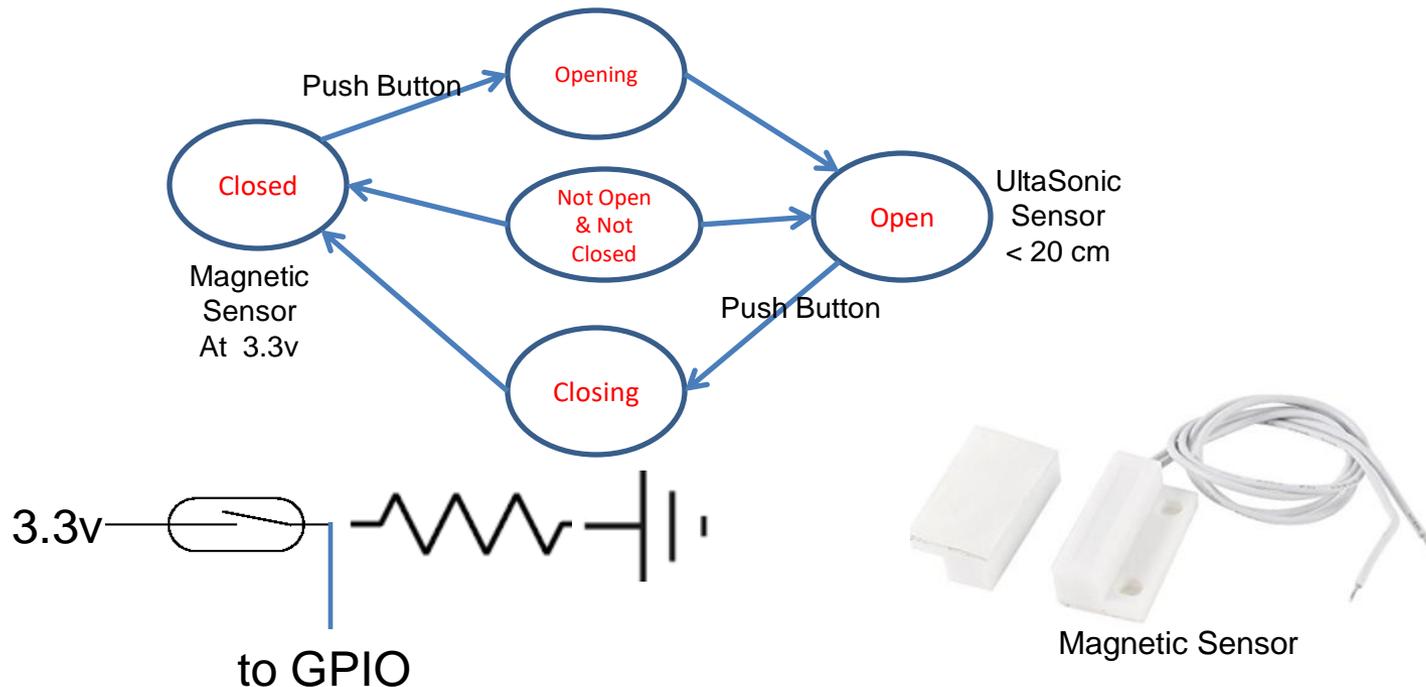
+ = 5V, - = Ground, S = signal (GPIO)  
NO = Normally open – connect to opener

# Demo Flow

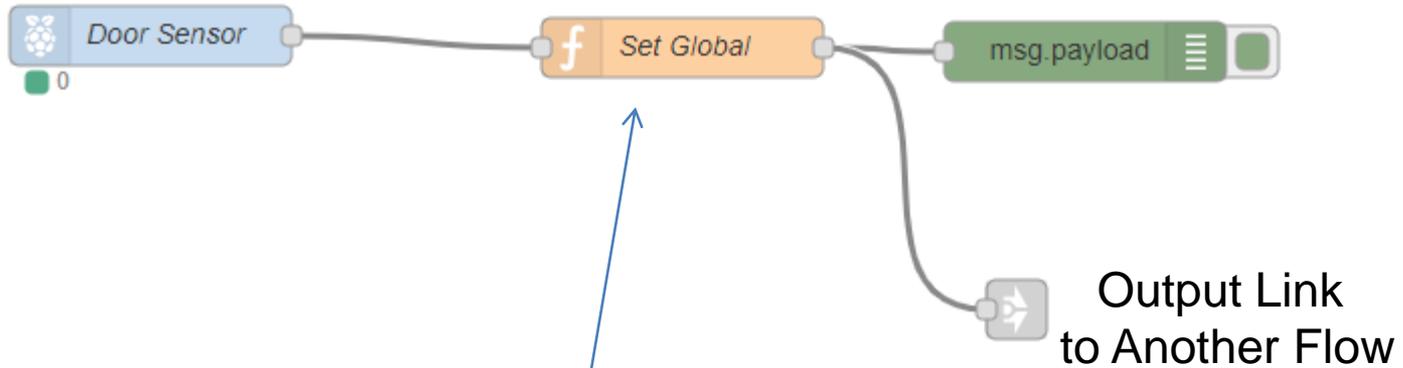


# Wait, wait there's more

- What if door is partially open or closed?
  - Possible solution: put magnetic sensor to detect when door fully closed. State diagram now:



# Flow for Door Sensor



`global.set('sensor',msg.payload+1)`

*Setting global = 2 if closed, 1 if open  
var x = global.get("sensor")  
(global.get thinks null if set = 0)*

# Alexa

- Pallet: node-red-contrib-wemo-emulator
  - Allows for Alexa to discover defined nodes as wemo lights
  - Limited to turn on/off, no special response back to Alexa
- Pallet: node-red-contrib-alexa
  - Setup AWS Skill, secure nod-red for https that AWS calls, port forwarding in your router
  - Will allow programming of requests and responses
  - No auto discovery
- Pallet: node-red-contrib-alexa-remote2
  - Can easily send announcements to Echo
  - Still learning about other capabilities
- Also might want:
  - Tell Alexa to open or close door
  - Announce via Alexa when door opened
  - Ask Alexa for status of door